Second Round Appraisal list

| Seq | No. | University | Topic | Test Room |
|-----|------|---------------------------------------|-------------------------------------------------------------------------------------------------------------------------------|--------------|
| 1 | 26-1 | Xi' an Jiaotong University | EEG-based control games using motor imagery BCI | 4-103 |
| 2 | 01-2 | Peking University | Research About the New Idea Touch Device | 4-103 |
| 8 | 31-1 | Arizona State University | ASU VIPLE and Minnowboard Robot Project | 4-105 |
| 6 | 20-1 | Shanghai Jiao Tong University | Security Specification of Robot Controlling Based On Gesture | 4-105 |
| 9 | 15-1 | Central China Normal University | Melody of Jingchu on the Chimes with the Robot | 4-104 |
| 11 | 08-1 | Northeastern University | Atom-Based Hand-Held B-Mode Ultrasound Diagnoser | 4-104 |
| 13 | 27-1 | Northwestern Polytechnical University | HalmaGo: Intelligent Halma Robot | 4-108 |
| 14 | 28-1 | Chongqing University | Wearable interaction device based on VR——COPYMAN | 4-108 |
| 3 | 05-1 | Beijing Institute of Technology | Depth of Field Imaging for Interactive Entertainment System | 4-103 |
| 4 | 03-1 | Beijing Jiaotong University | Intelligent Chinese Eight-ball Robot | 4-103 |
| 7 | 19-1 | Shanghai University | The Online Rehabilitation Training and Evaluation System on the Integration of Upper and Lower Extremities of Stroke Patients | 4-105 |
| 5 | 17-1 | Nanjing University | Watchman of the Cityan intelligent aerocraft for urban service and management | 4-105 |
| 12 | 24-1 | Wuhan University | Genius Arm-An Intelligent Exploration Robot controlled by EMG Signals | 4-104 |
| 10 | 09-1 | Fudan University | UAV-Based Large Scale Preciseoutdoor Object Reconstructing System | 4-104 |
| 15 | 17-2 | Nanjing University | Magic Volumetric Display System | 4-108 |
| 16 | 23-3 | Tongji University | Indoor Autonomous Security Patrol Robot | 4-108 |